

Paper 8 – Discussion

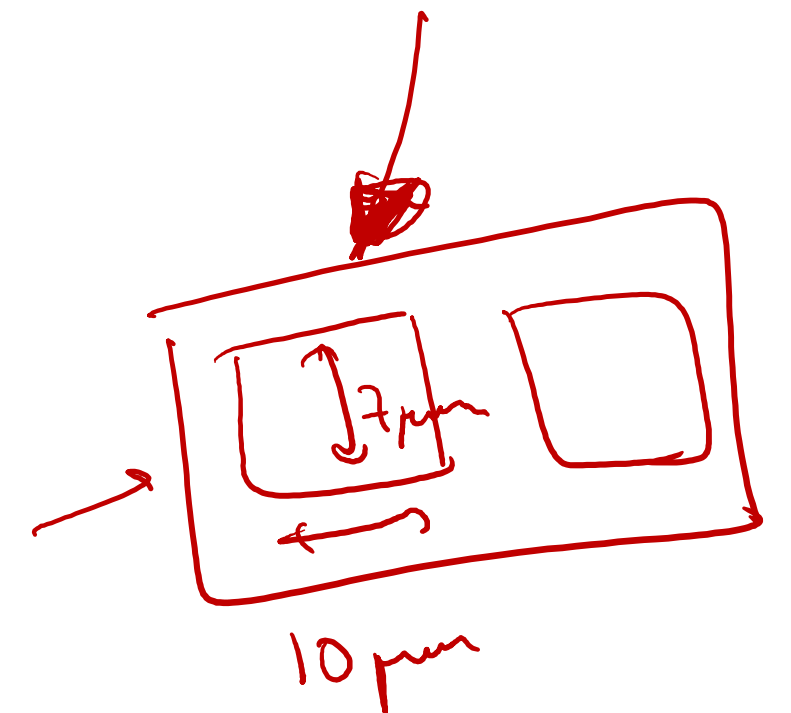
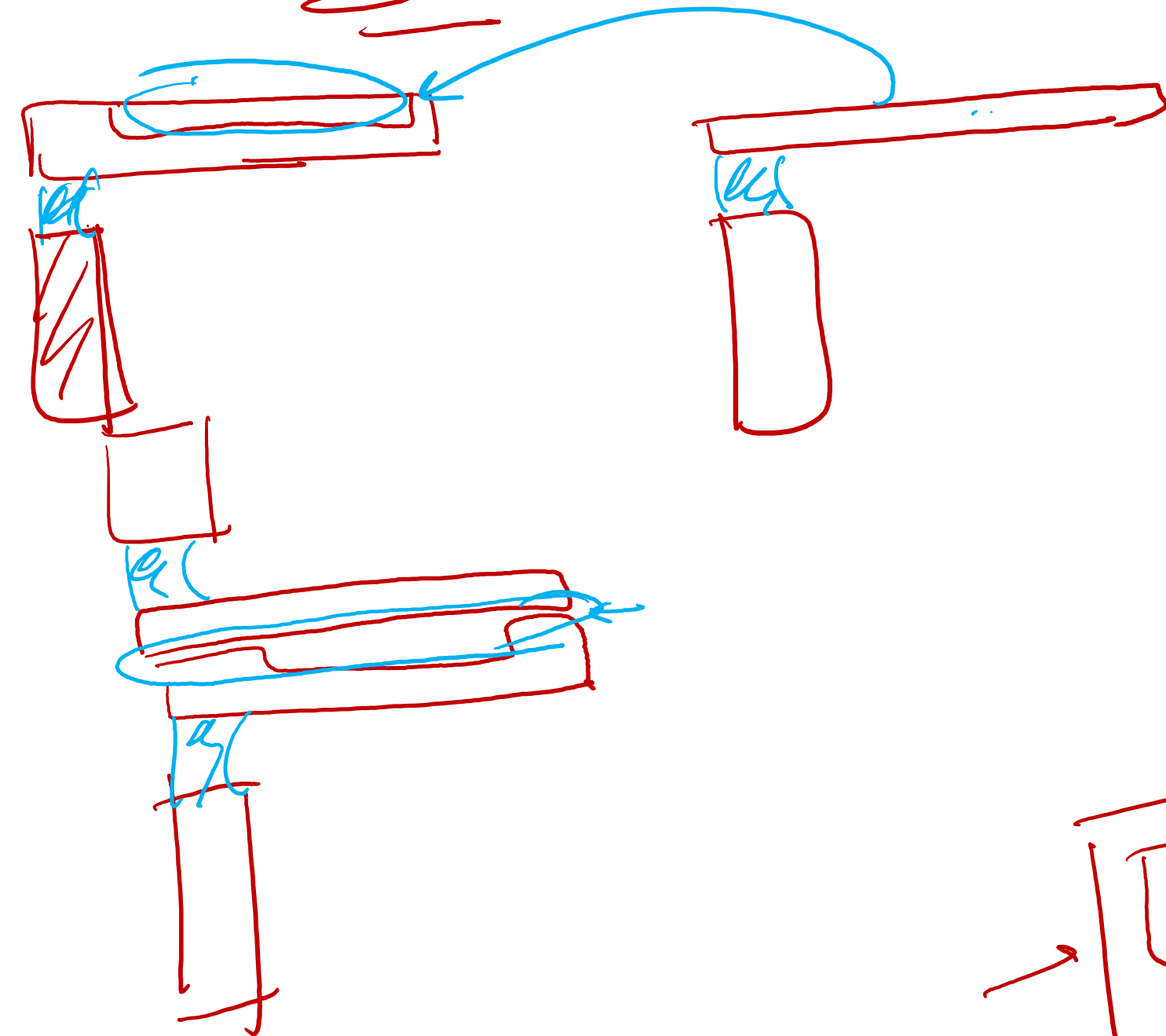
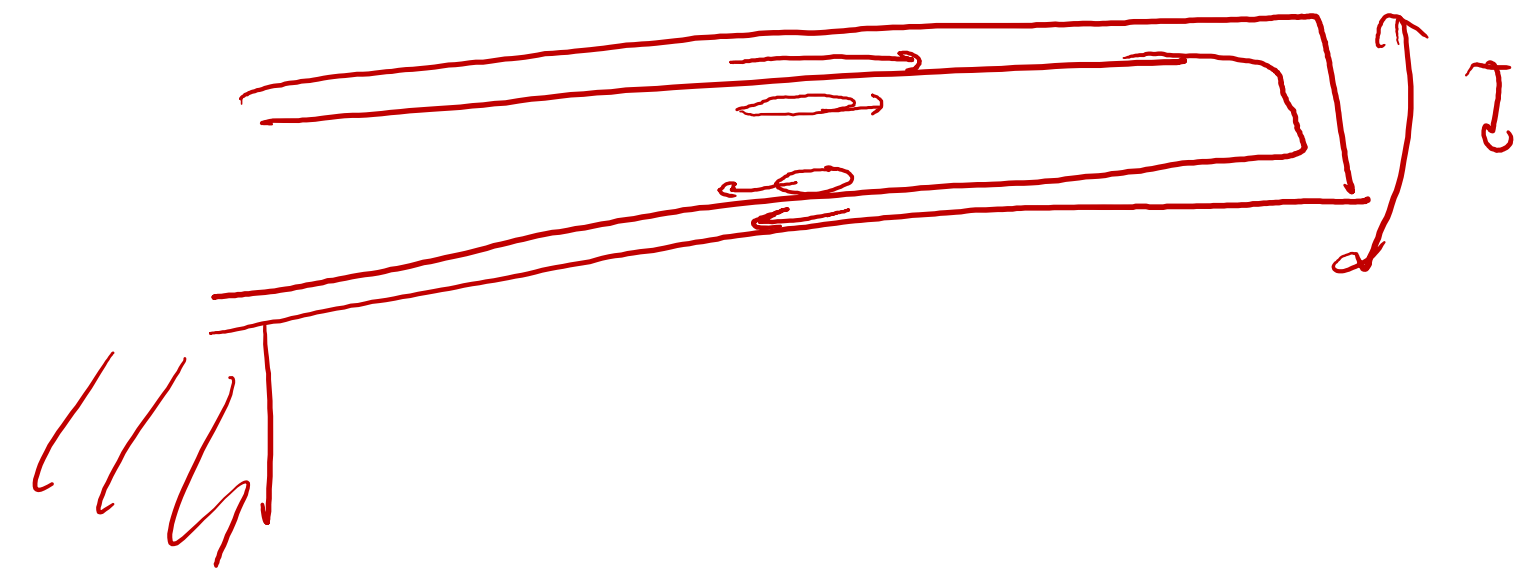
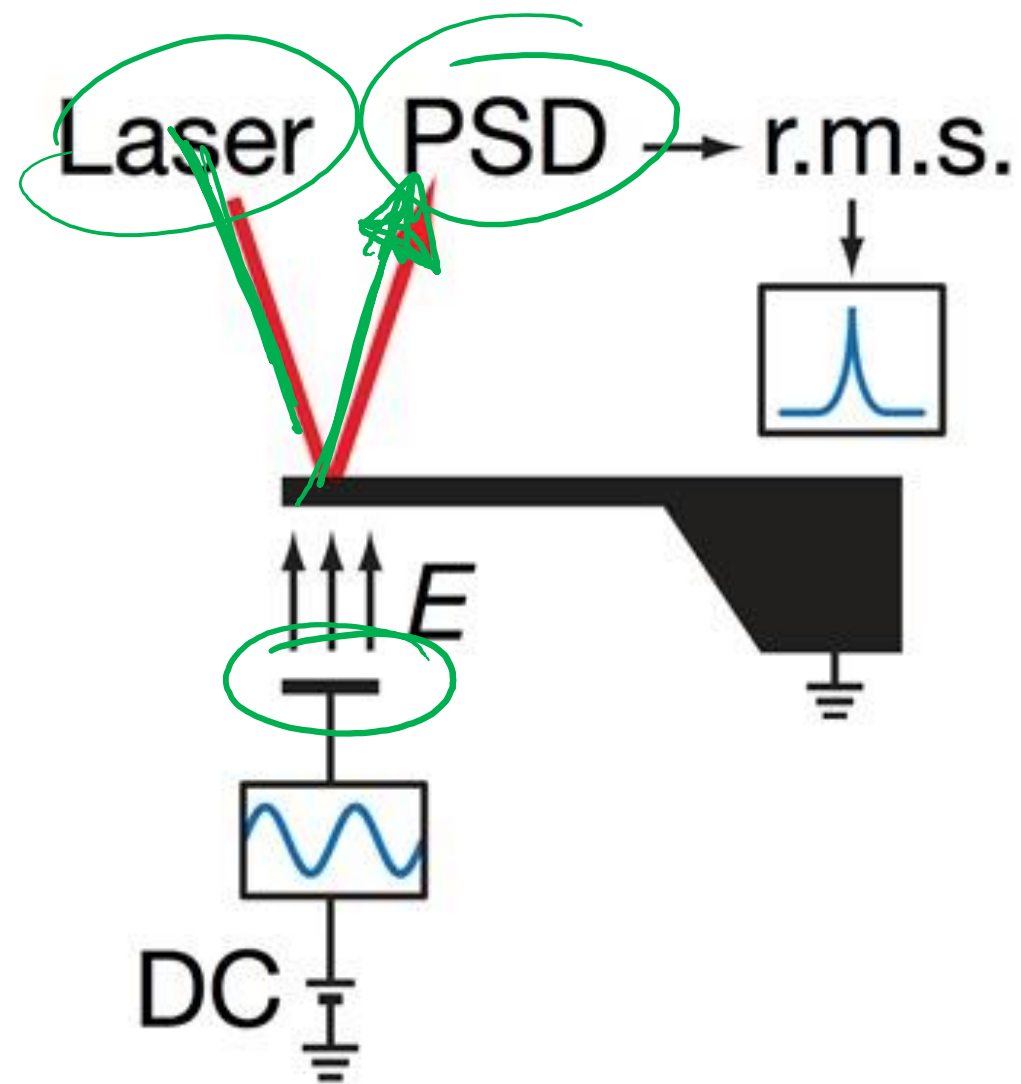
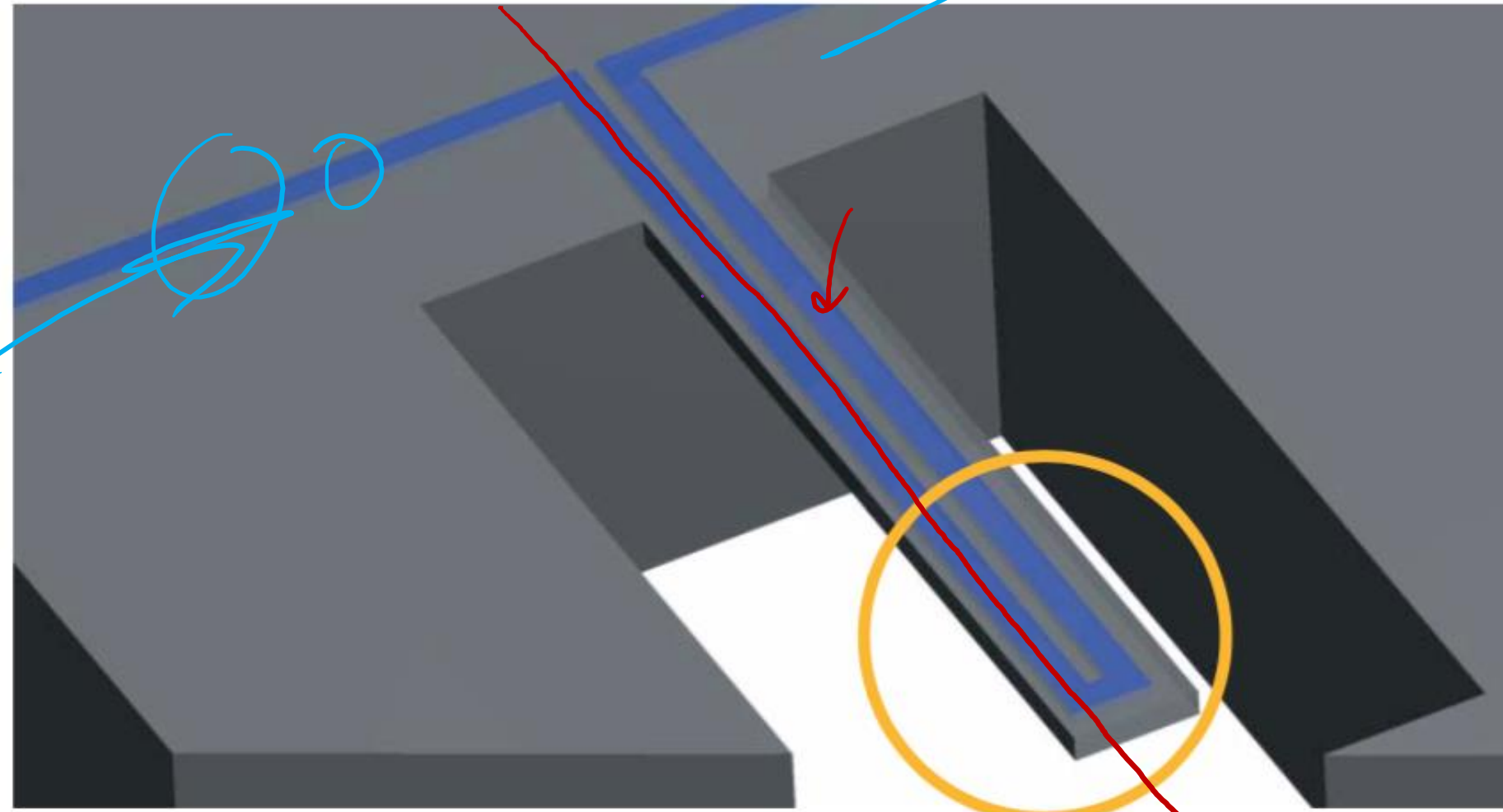
ME-426 – Micro/Nanomechanical Devices

Prof. Guillermo Villanueva

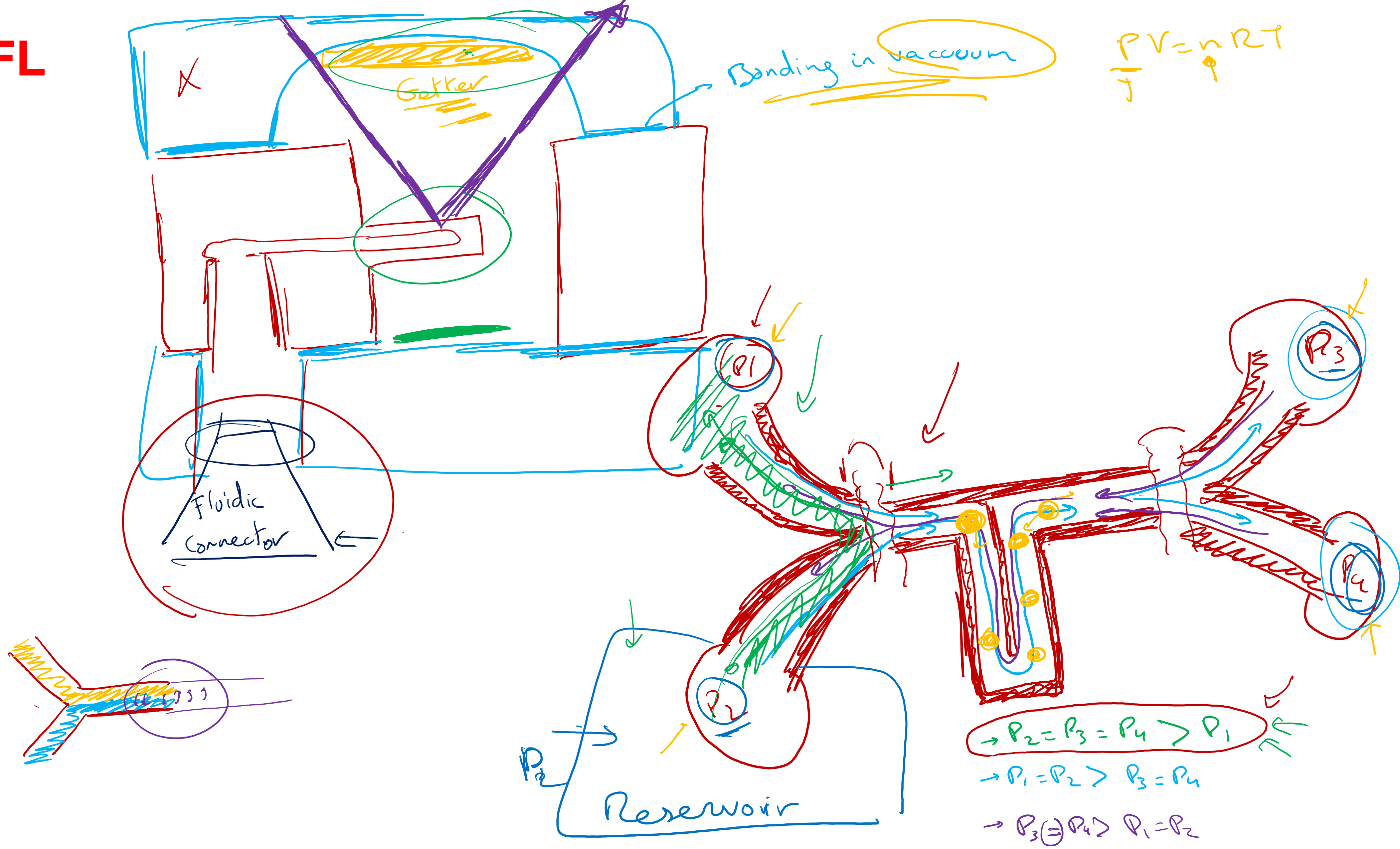
Noise in $\omega \rightarrow \frac{1}{Q}$; $Q \uparrow \Rightarrow \text{Noise} \downarrow$

- What is the main characteristic of these devices?
- How are the devices made? Isn't it very expensive? What is a getter?
- How are the devices actuated and detected?
- How fast is the liquid flowing? $\leftarrow$
- Is there a problem with viscous fluids, with capillary forces, with turbulence?
- What is that "alpha" parameter in the mass responsivity?
- Why is there an 8% dispersion due to the position? How to avoid it? ✓
- Differences between in-flow and attachment solutions
- Can we use this as a Coriolis-force sensor?

EPFL Discussion

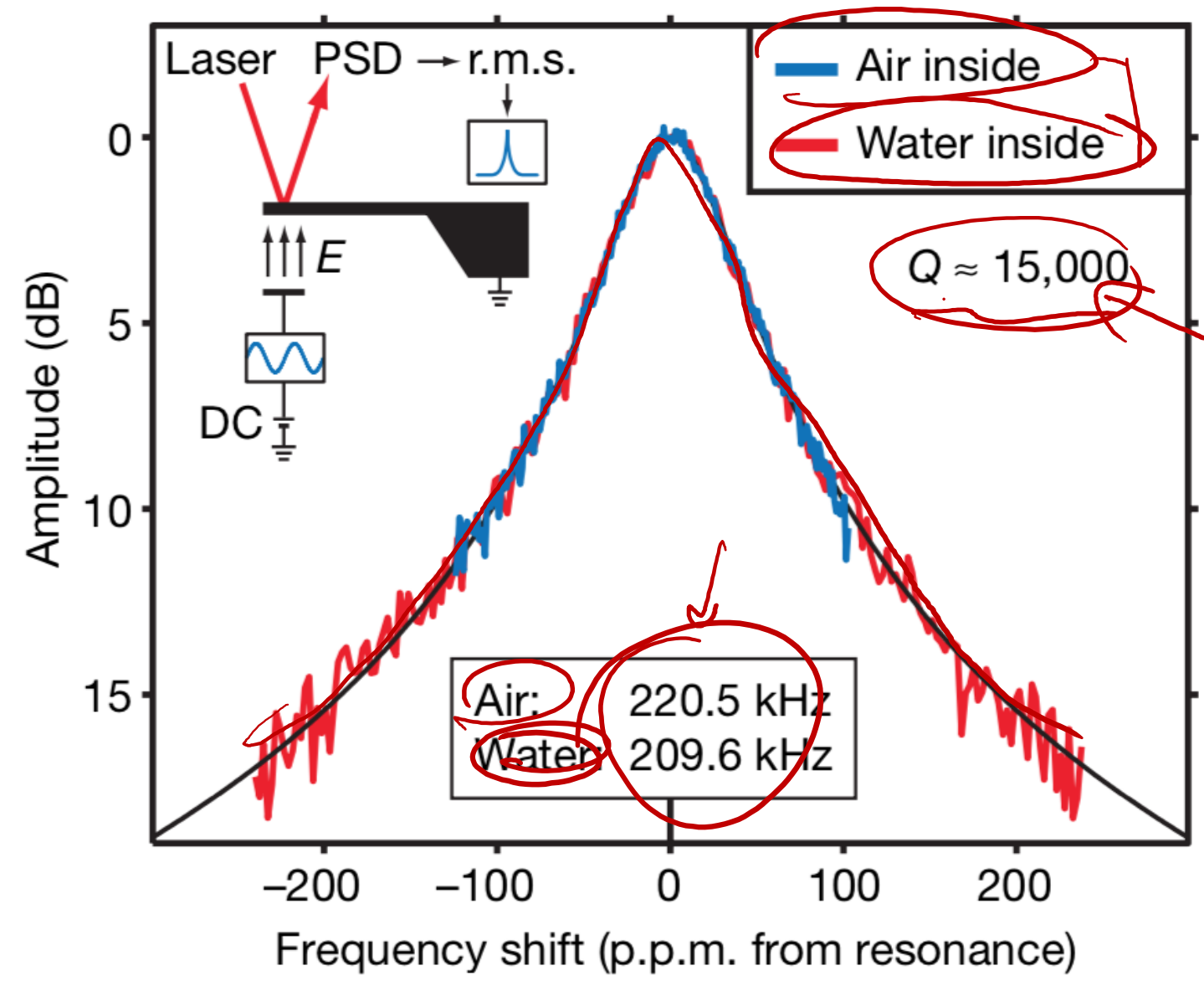


R.B.C. $\Rightarrow \phi \sim 6 \mu\text{m} \Rightarrow \text{Capillaries} < \underline{\underline{2 \mu\text{m}}}$

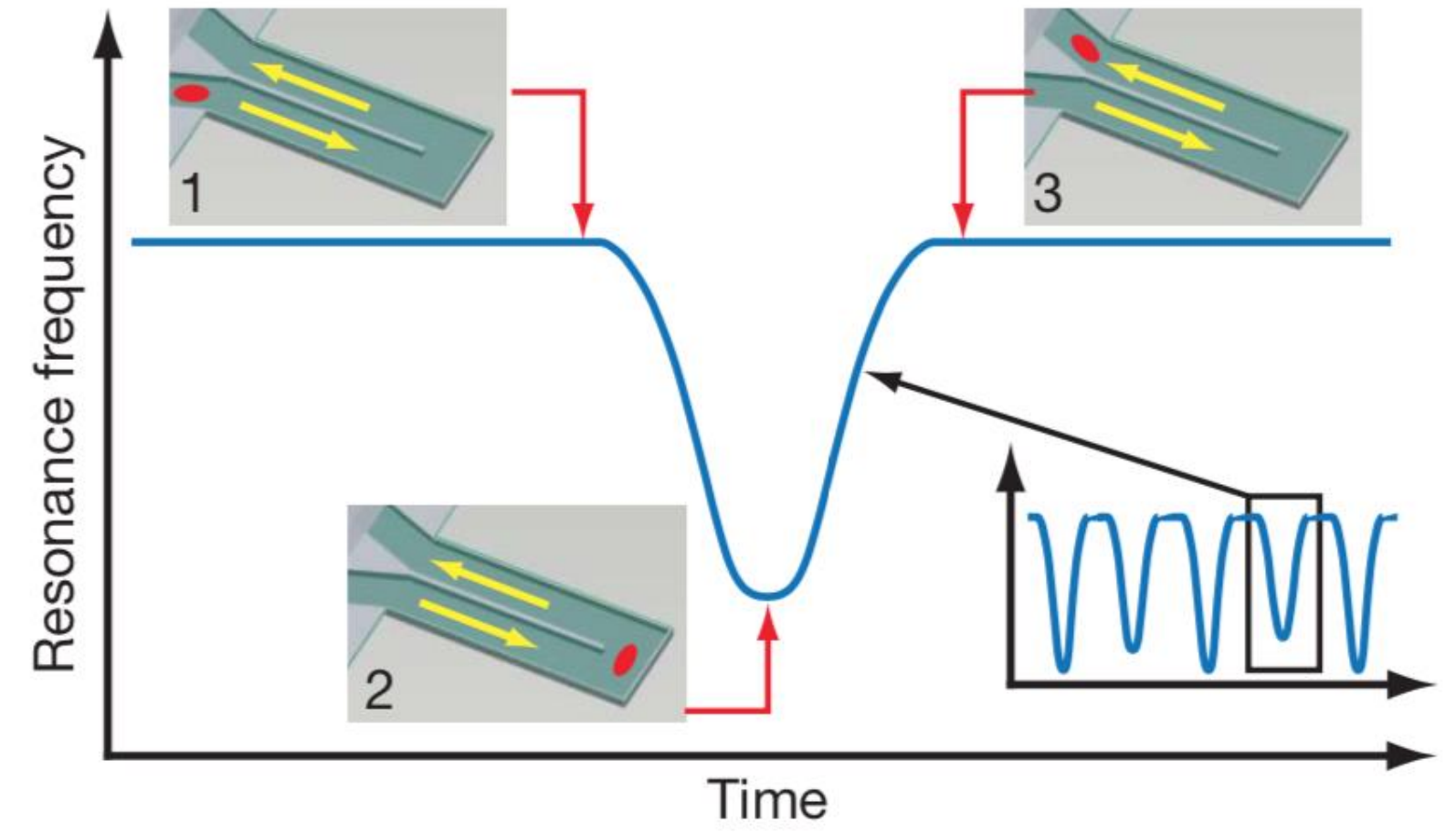
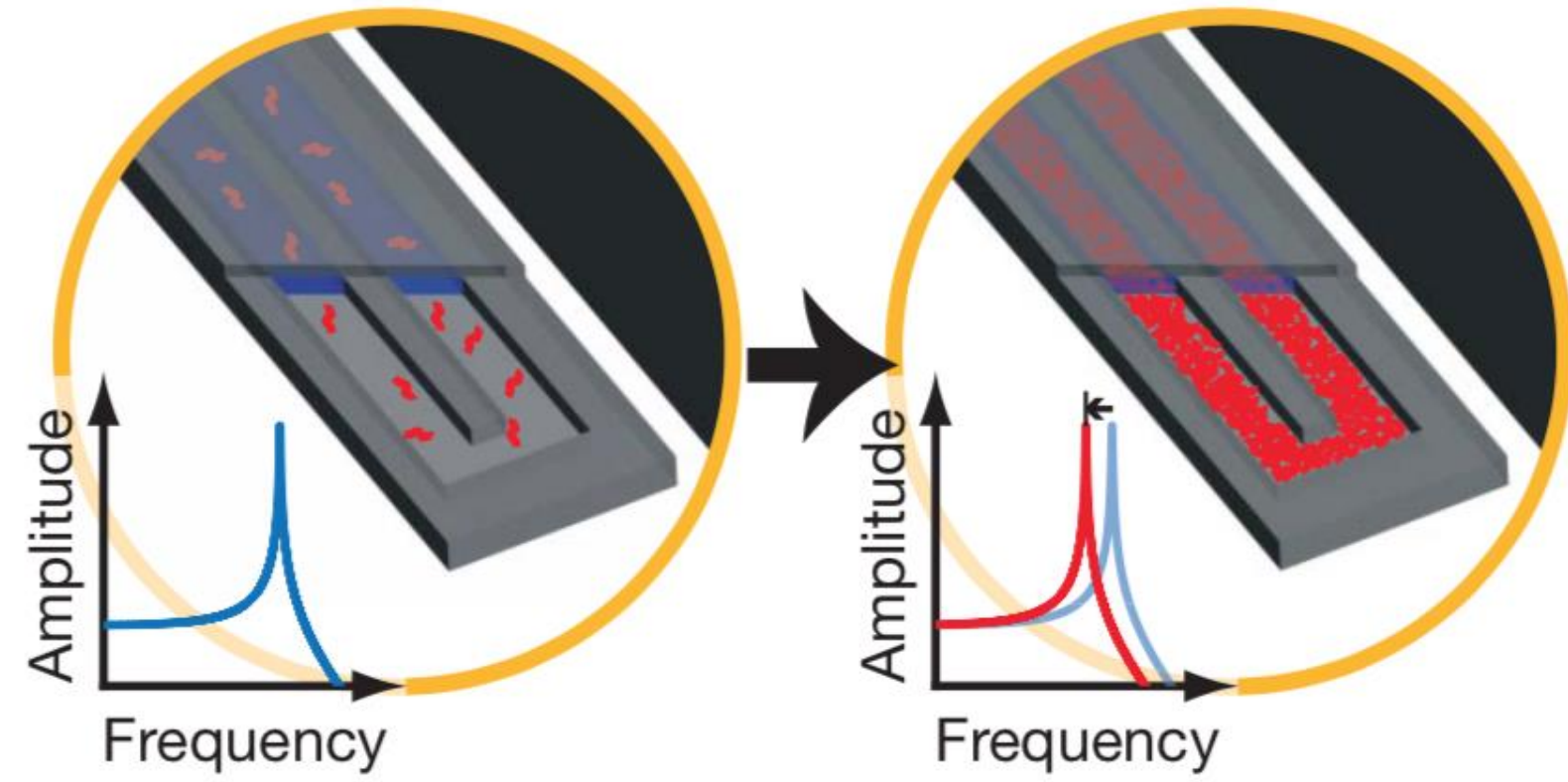


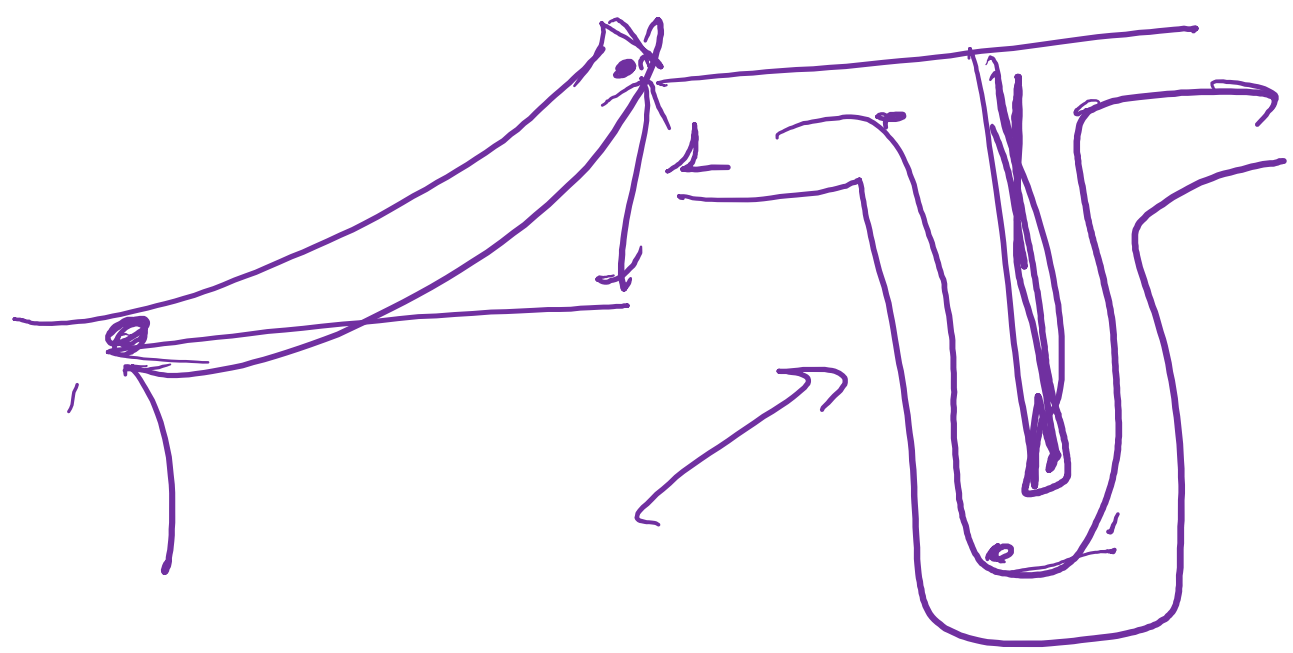
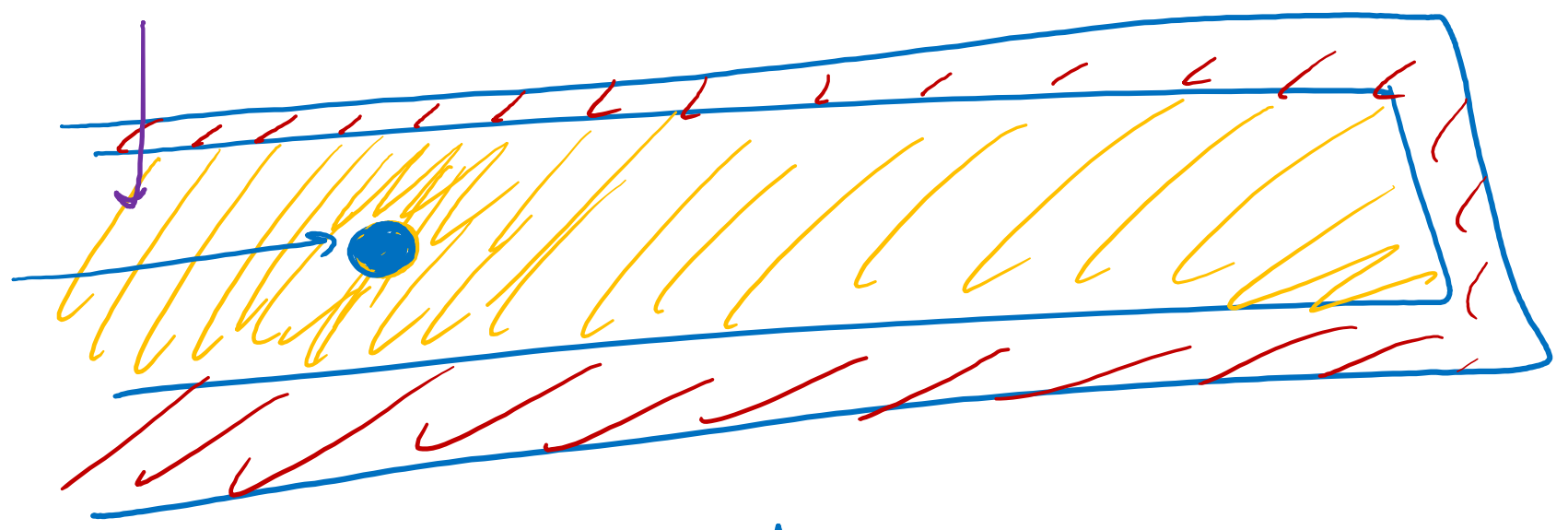
$$PV = nRT$$

EPFL Discussion



EPFL Discussion



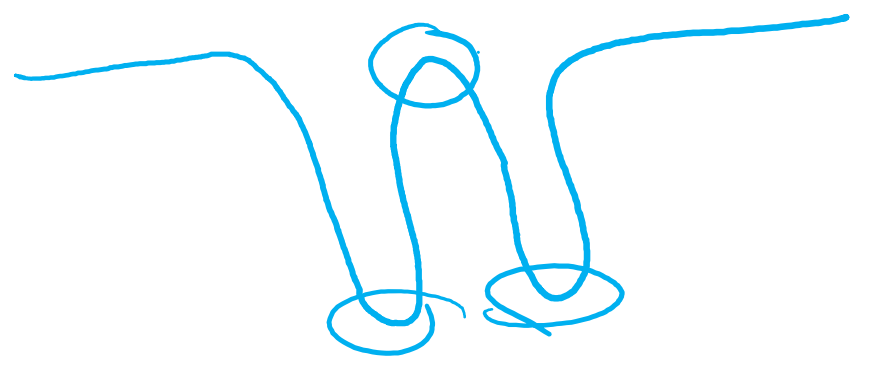
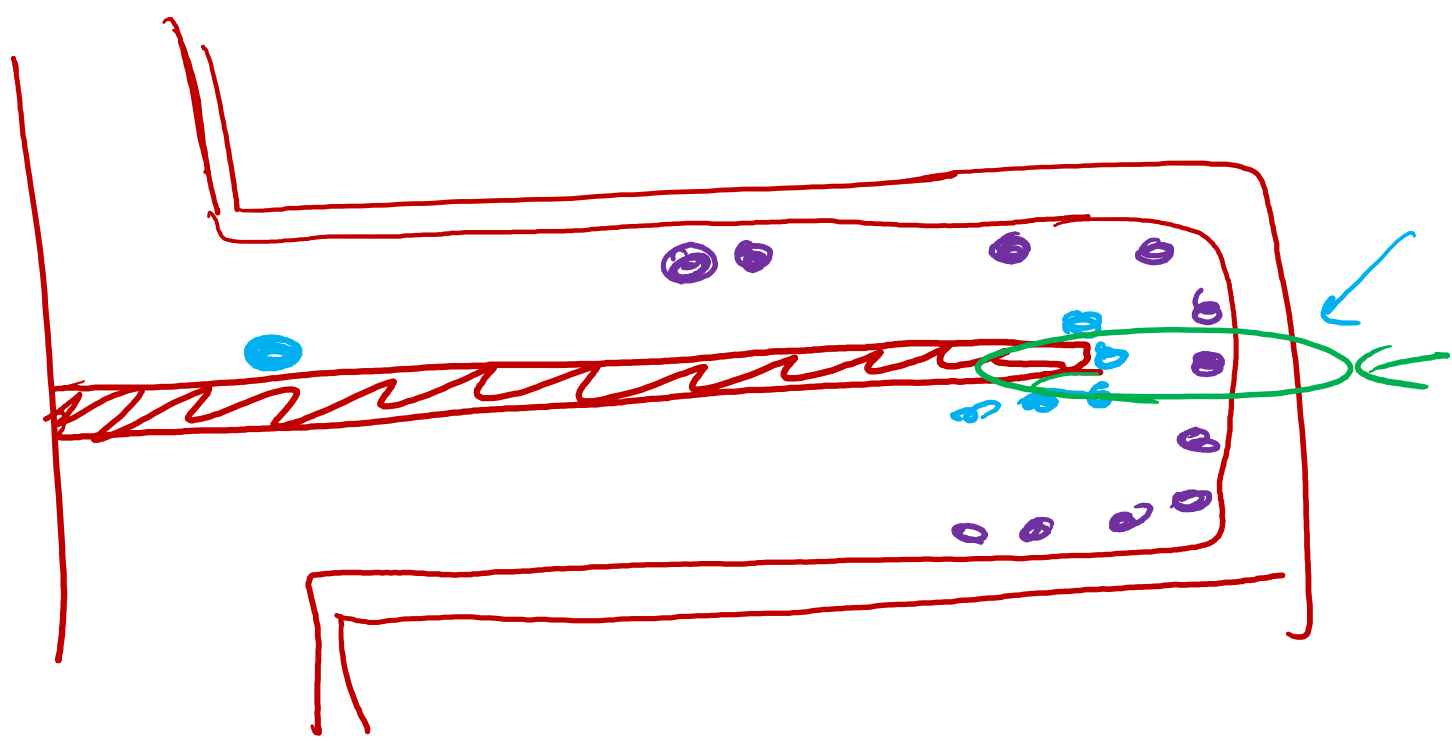
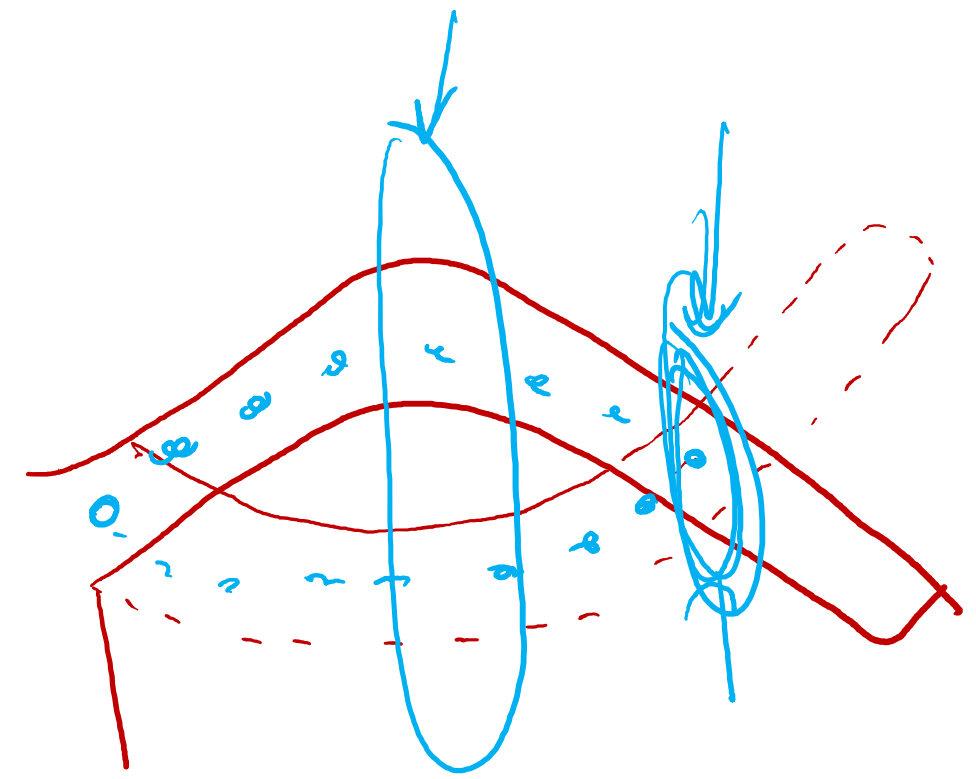


$$m_{eff} = \int \phi_n^2 \cdot dm$$

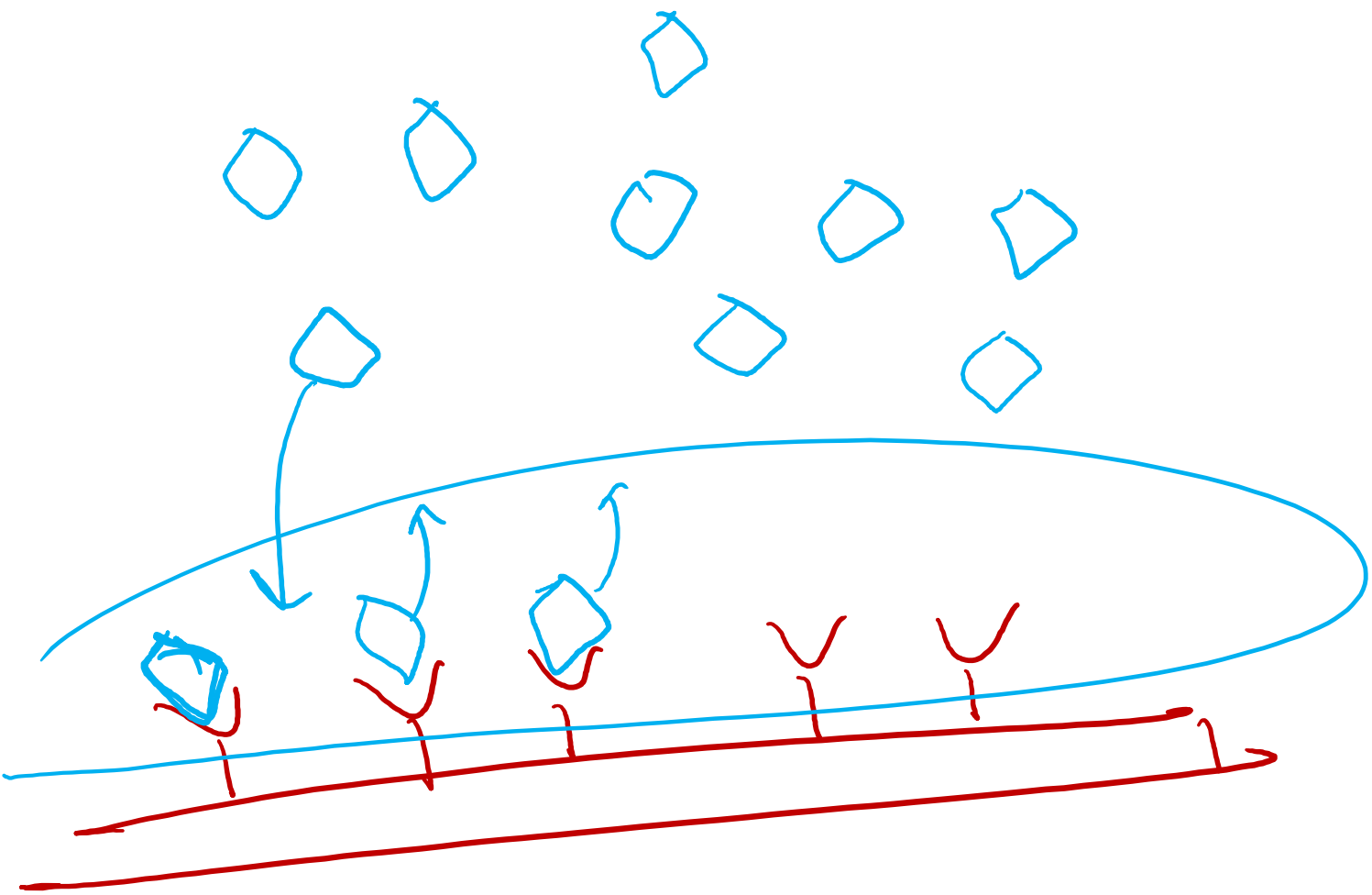
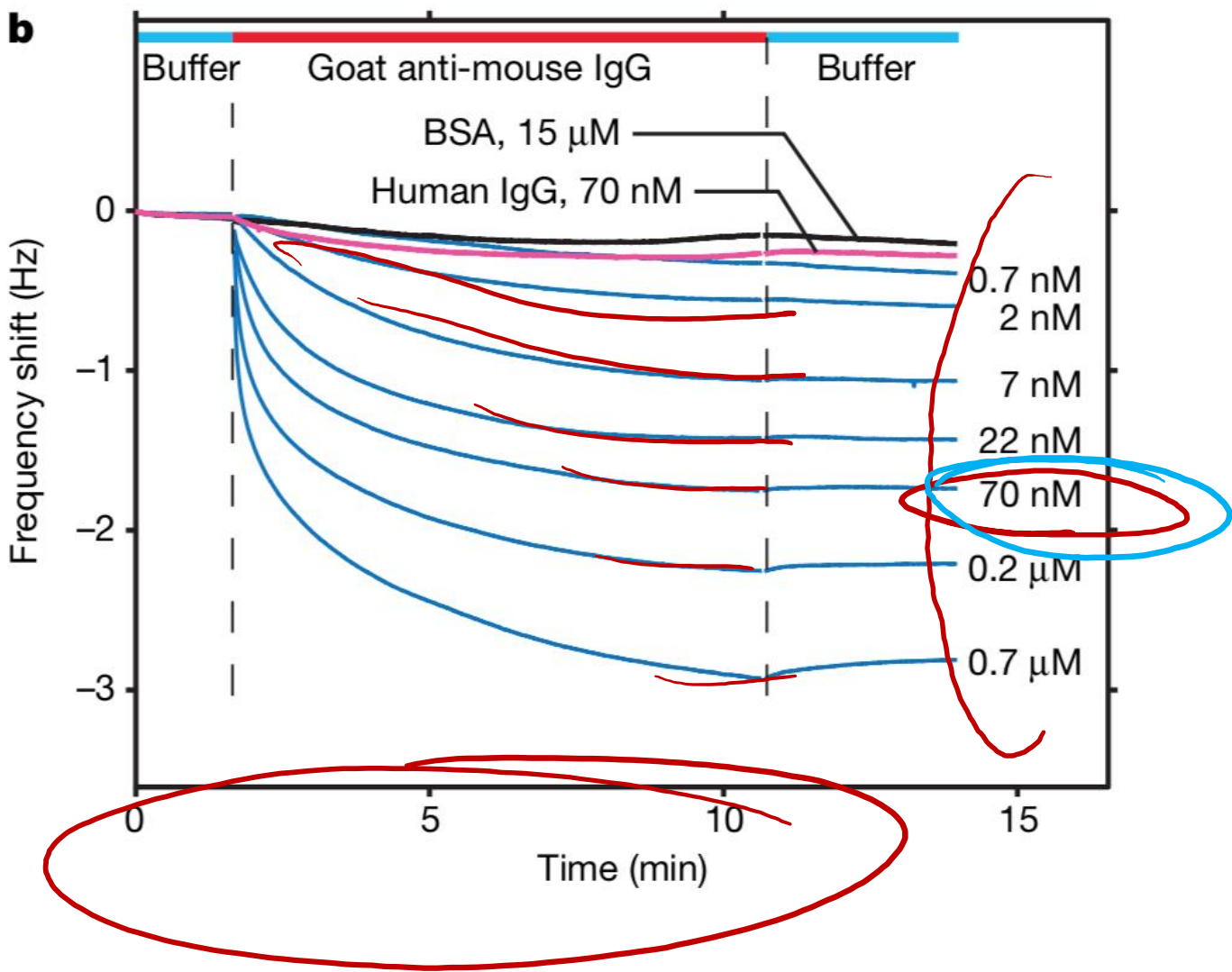
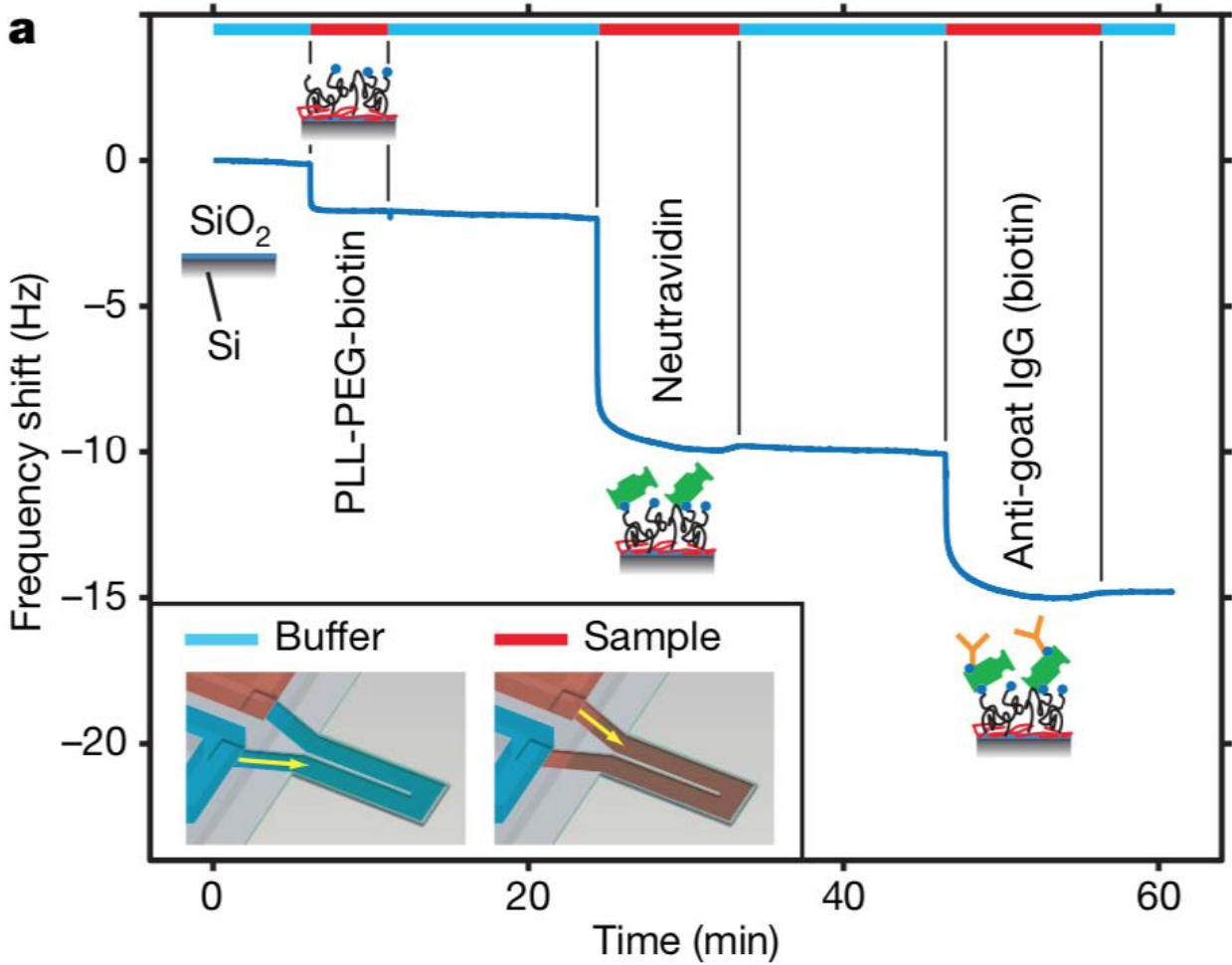
$$m_{eff} = \int_{Si} \rho_{Si} \phi_n^2 \cdot dV + \int_{WATER} \rho_{WATER} \cdot \phi_n^2 \cdot dV +$$

$m_{eff, no particle}$

$$\left(\rho_{part.} - \rho_{water} \right) \phi_n^2 \cdot \delta(x) \cdot dV$$
$$\left(\rho_{part.} - \rho_{water} \right) \phi_n^2(x_{part.}) \cdot V_{part.}$$



EPFL Discussion



EPFL Discussion

